





The 24th IEEE International Conference on Intelligent Transportation Systems (ITSC 2021) Best Student Paper Award – 2nd Place

"Learn Collision-Free Self-Driving Skills at Urban Intersections with Model-Based Reinforcement Learning"

Guan, Yang; Ren, Yangang; Ma, Haitong; Li, Shengbo Eben; Sun, Qi; Dai, Yifan; Cheng, Bo Tsinghua University (China)

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Professor Yaobin Chen General Chair, IEEE ITSC2021 Professor Lingxi Li Program Chair, IEEE ITSC2021